

## Digibus® Austria - Automated shuttles for the first/last mile in public transport

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PRISMA solutions, Austria

Presentation at CIVINET webinar, May, 19<sup>th</sup> 2021

### Coordinator



### Associated Partners



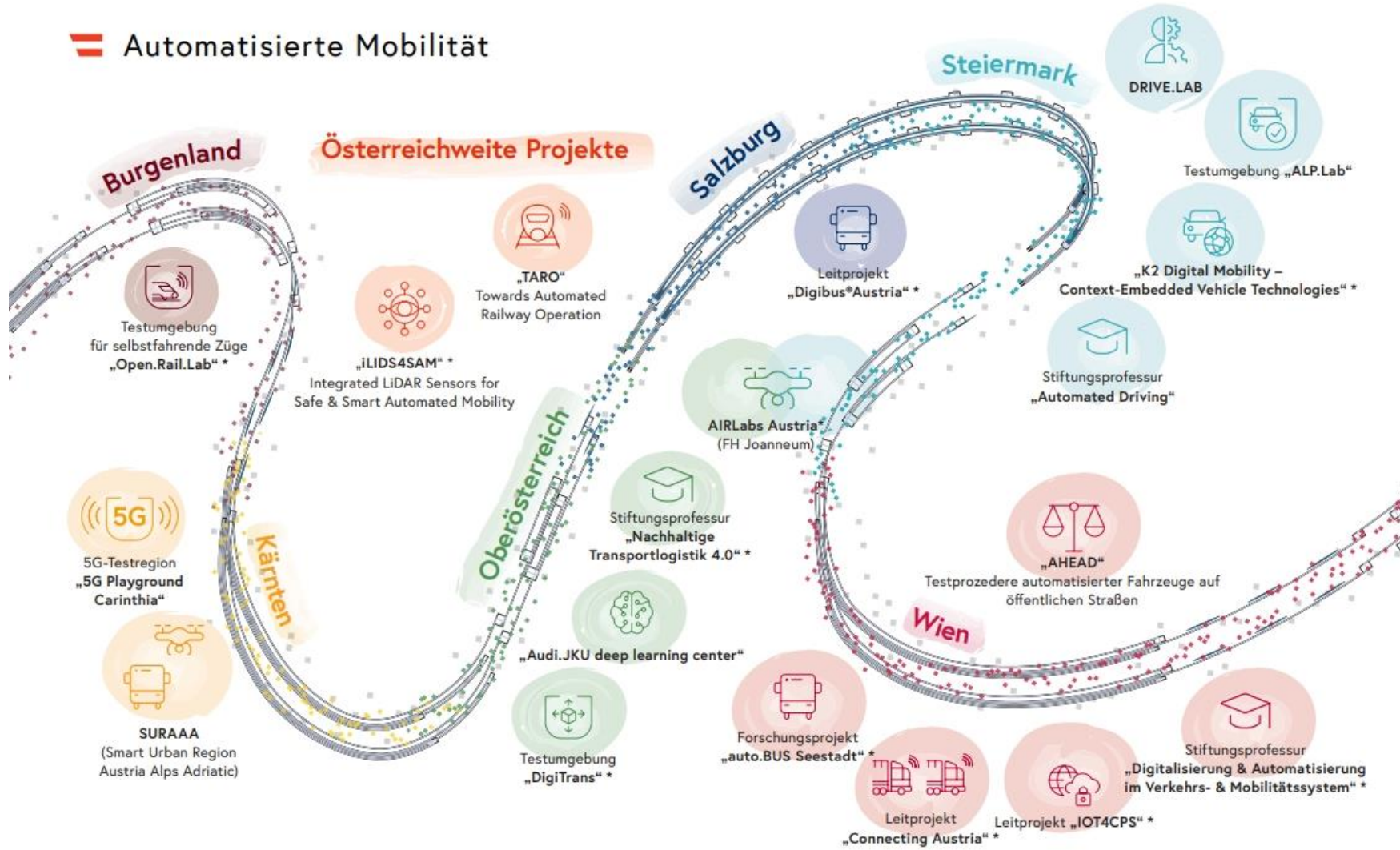
### Partners



### Funded by



# Automated mobility in Austria



\* Die aufgelisteten Projekte stellen einen Auszug aller BMK-unterstützten Projekte zur automatisierten Mobilität in Österreich dar. Darüber hinaus unterstützt das BMK eine Vielzahl an interdisziplinären Projekten aus den Bereichen Informations- und Kommunikationstechnologien, Mobilität und Sicherheitsforschung.

Besuchen Sie uns doch auf der Website des BMK zu automatisierter Mobilität!



Source: [https://www.bmk.gv.at/themen/mobilitaet/alternative\\_verkehrskonzepte/automatisiertesFahren/kompetenzkarte.html](https://www.bmk.gv.at/themen/mobilitaet/alternative_verkehrskonzepte/automatisiertesFahren/kompetenzkarte.html)



# 36 Months of Research with the Digibus®

Digibus®  
Austria



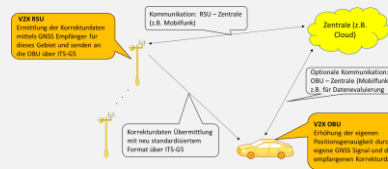
2021/05/19



# The flagship project Digibus® Austria

**Digibus®**  
Austria

## Digital infrastructure & connectivity



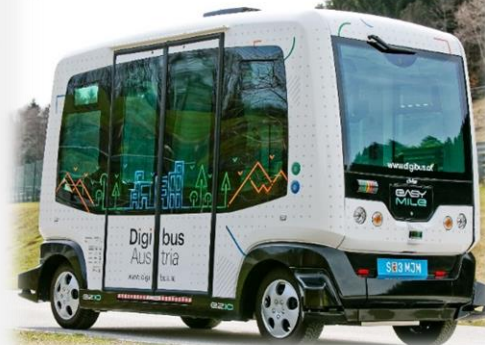
**AIT**  
Austrian Institute of Technology

**salzburgresearch**

**kapsch**

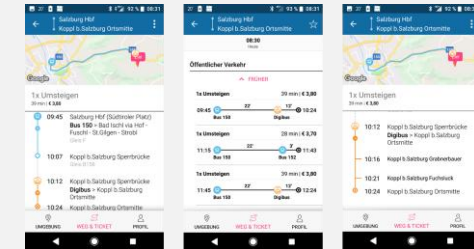
**easy MILE**  
PRISMA solutions

**Digibus®**  
Austria



Source: Salzburg Research / wildbild

## Automated mobility system & passenger interaction



**ÖBB**

**Fluidtime**

**BOKU**

**AIT**  
Austrian Institute of Technology

**COMEND**

## Driving scenarios & interaction with other road users



**virtual vehicle**

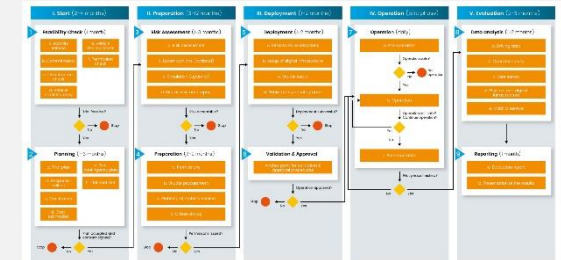
**Center for Human-Computer Interaction**  
University of Salzburg

**FACTUM**  
MOBILITY · RESEARCH · INNOVATION

**easy MILE**

3 years runtime (2018-2021)  
13 partners  
4.2 million EUR budget

## Reference model for deployment & operation of automated shuttles

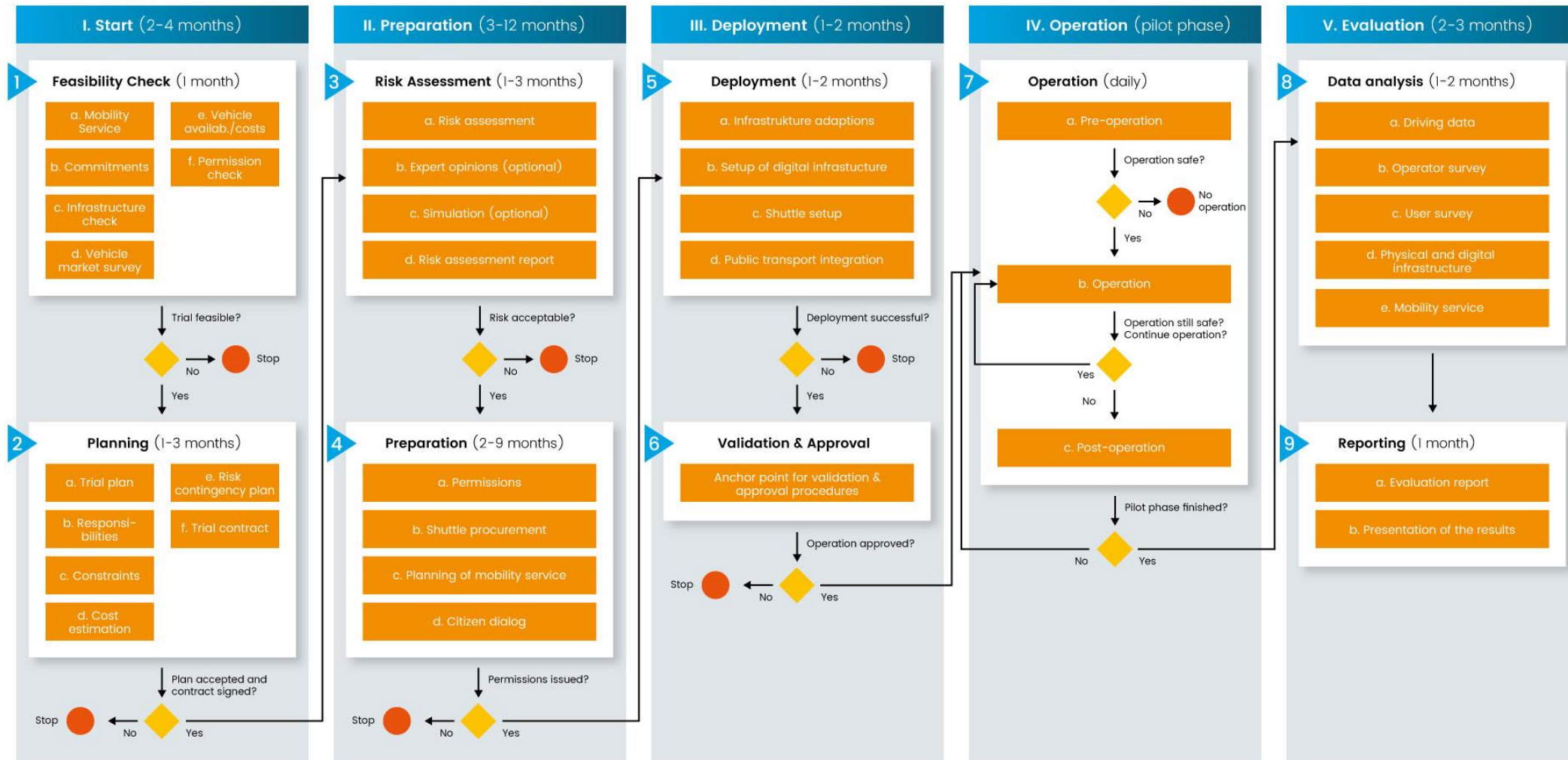


**salzburgresearch**

**HERRY**  
Verkehrsanalyse · Beratung · Forschung

**PRISMA**  
solutions

# Digibus® Austria Process Model for the Operation/Trial of Automated Shuttles

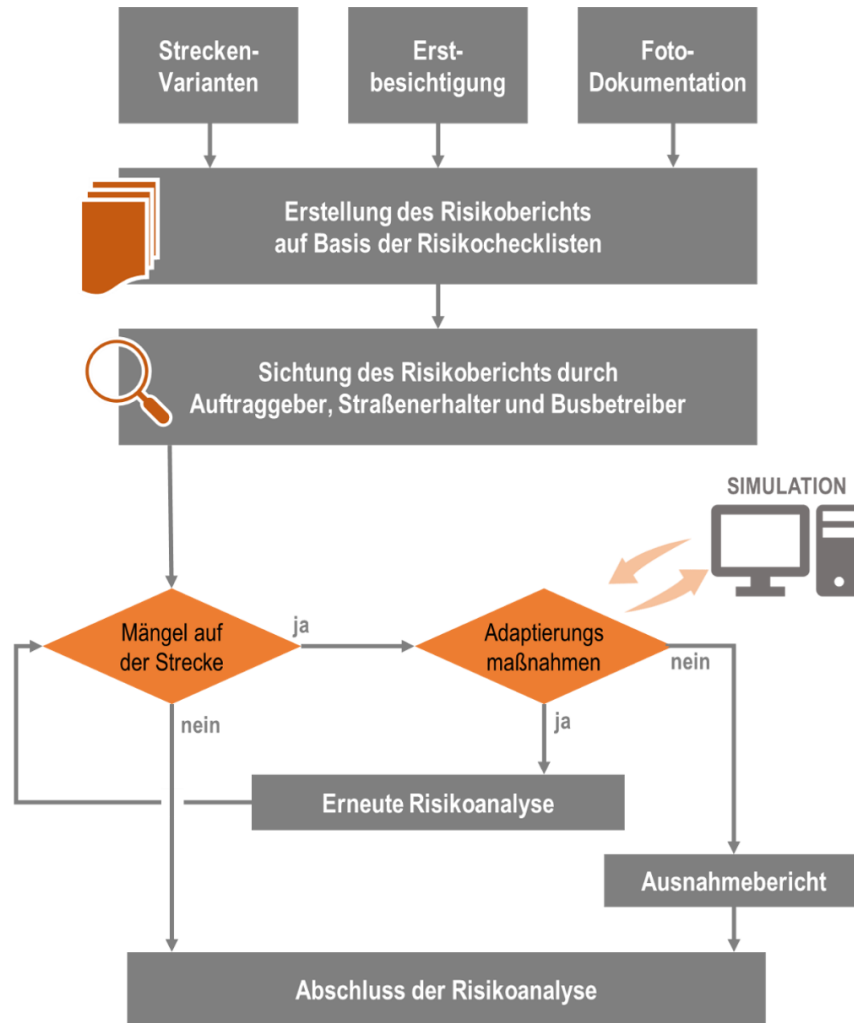


# Phase II: Risk Assessment



- How can the risk for operating an automated shuttle be systematically assessed?
- How can simulation contribute to virtual risk assessment?

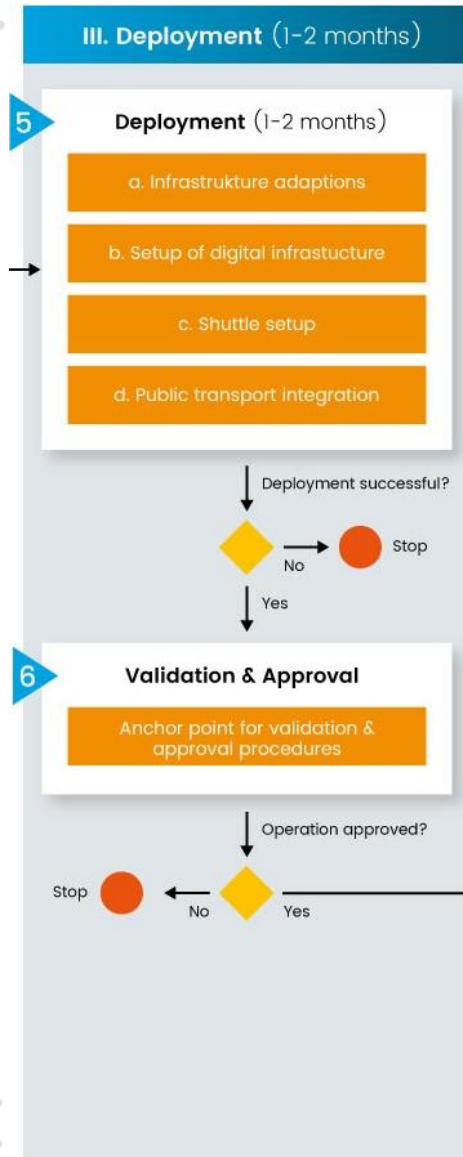
# Phase II: Risk Assessment - Method



- Collection of data
  - Selection of route variants
  - Local inspection
  - Photo documentation
- Risk assessment based on risk checklists
  - Definition of risk mitigation measures
  - Optional: Virtual risk assessment for risky route parts (simulation)
- Several iterations if necessary



# Phase III: Deployment / Virtual Infrastructure



- How can virtual infrastructure support an automated shuttle?



# Phase III: HD Map – Methodology

## Methodology for generating a lane-accurate road model and driving path for automated passenger shuttles

1

### Feature catalogue

Datenkategorie	Streckenplanung	Risikobewertung und Simulation	Fahrerassistenz	ETSI ITS-G5 Map 1
<b>Verkehrsflächen</b>				
Fahrbahnen	✓	✓	✓	✓
Bushaltestelle	✓	✓	✓	✓
Gehsteig und Fahrradweg, Fußgängerübergang und Fahrradüberfahrt	✓	✓	✓	✓
Sperrfläche, Grünfläche		✓	✓	
Parkplatz, Parkstreifen		✓	✓	
<b>Abgrenzungen zwischen Verkehrsflächen</b>				
Mittel- und Begrenzungslinie	✓	✓	✓	✓
Begrenzungsinfrastruktur		✓	✓	
<b>Verkehrsregeln</b>				
Verkehrszeichen	✓	✓	✓	✓
Stopp- und Halteflächen, Vorrangregeln, Richtungspläne	✓	✓	✓	✓
Lichtsignalanlage		✓	✓	✓
<b>Infrastruktur</b>				
Tunnel und Brücke	✓	✓	✓	✓
Leitpfad, Straßenlaternen		✓	✓	
Gebäude		✓	✓	
Andere Objekte		✓	✓	

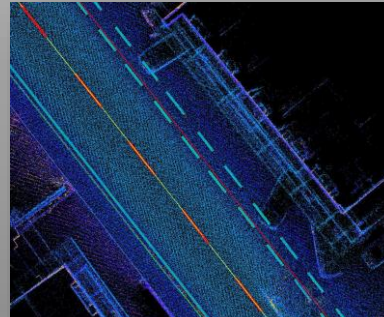
2

### Data collection



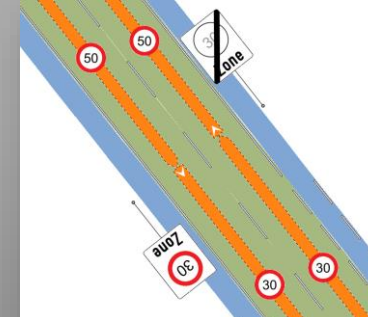
3

### Feature extraction



4

### Map composition



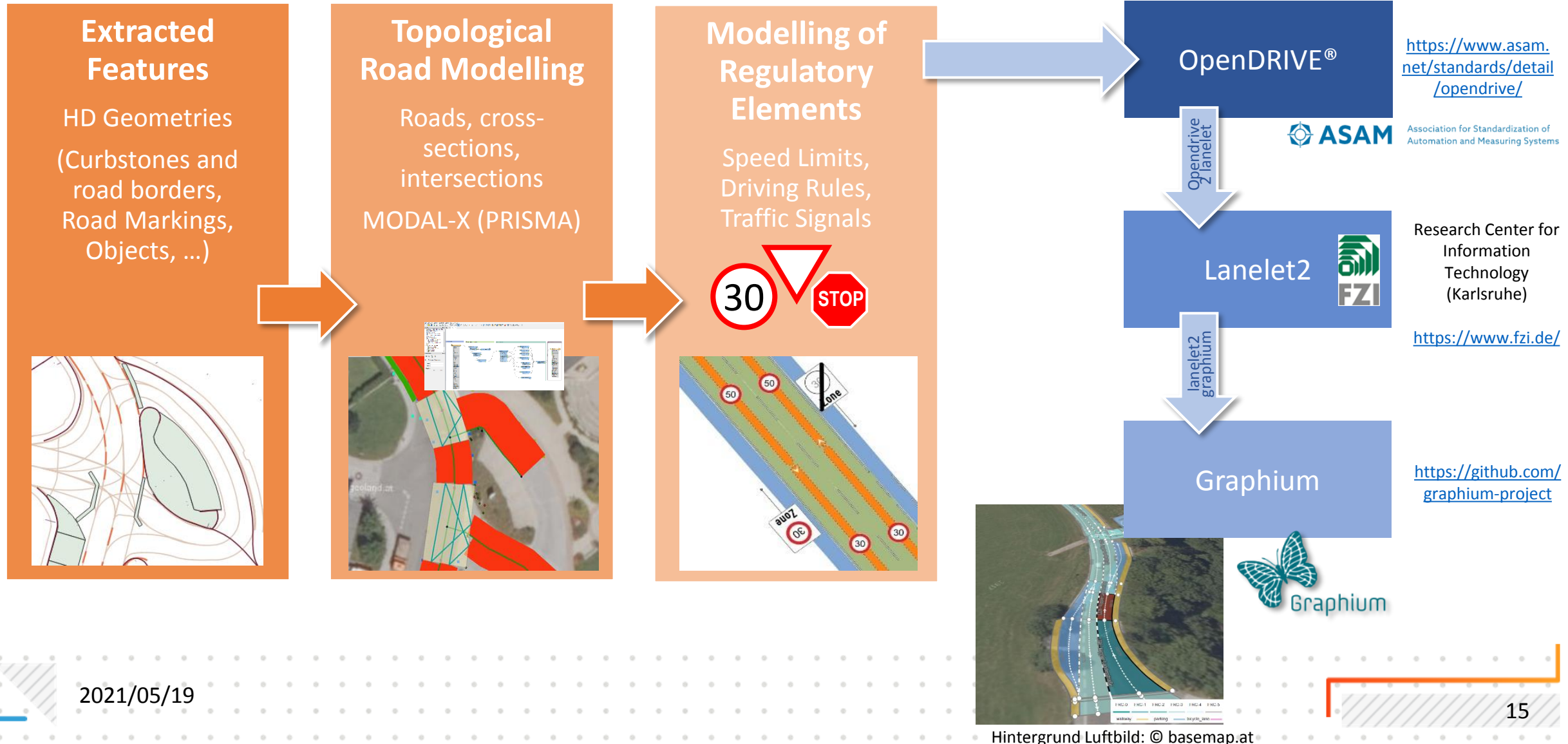
5

### Centerline generation



# Phase III: HD Map – Map Composition

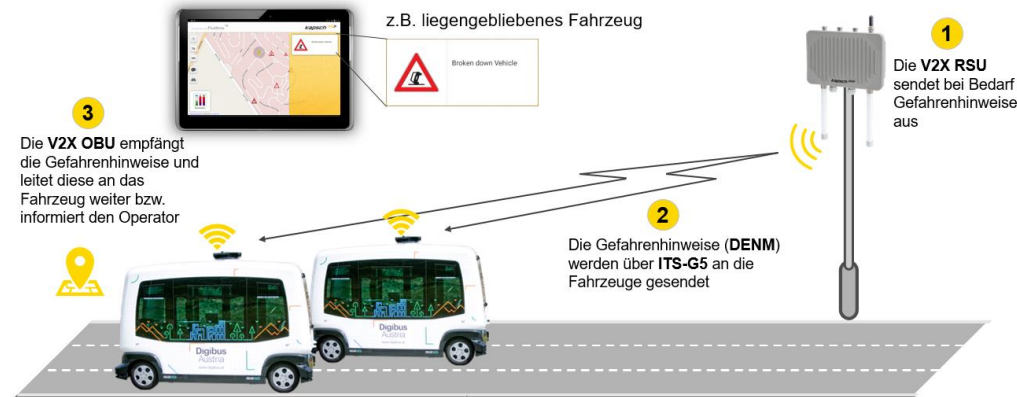
## HD Map Formats





# Phase III: Digital Infrastructure / V2X / C-ITS

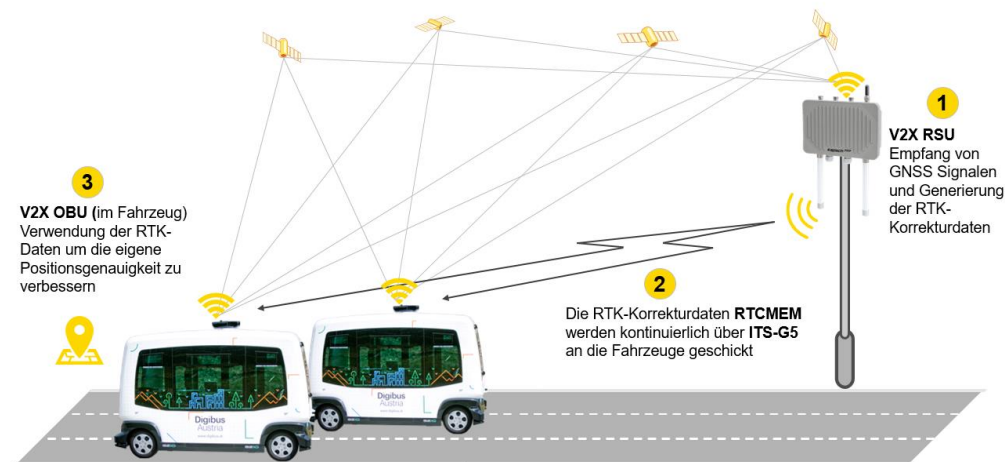
## Warnings: ITS-G5 DENM



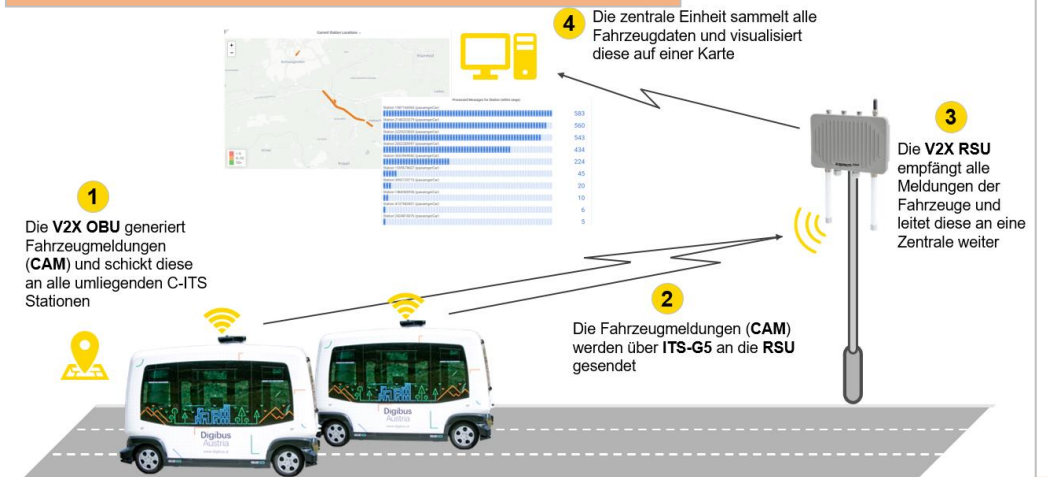
## Signal Phases: ITS-G5 SPaT/MaP



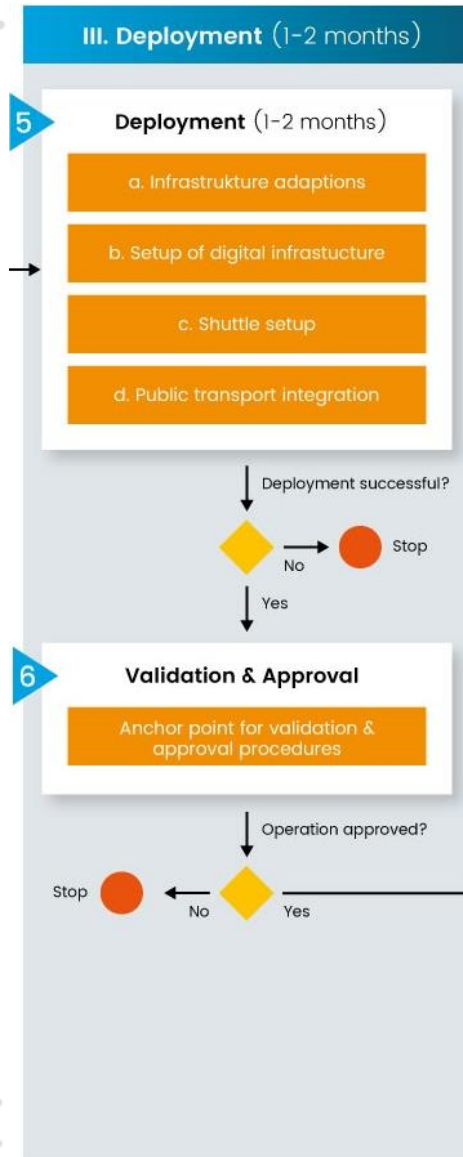
## Accurate positioning: ITS-G5 RTCMEM



## Vehicle Awareness: ITS-G5 CAM



# Phase III: Integration into the Mobility System



- How can an automated shuttle be integrated into a regional mobility system?





# Phase III: Integration into the MaaS-App wegfinder

Digibus<sup>®</sup>  
Austria

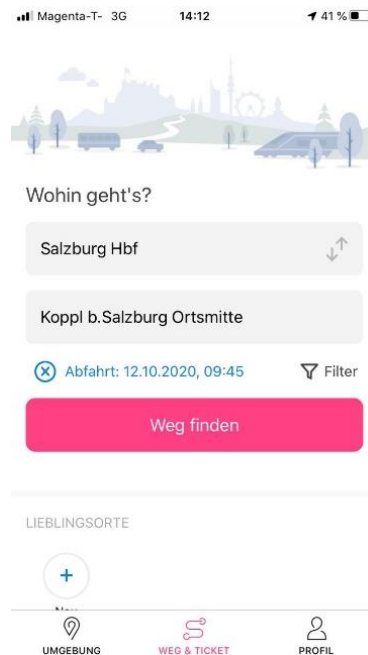


wegfinder

1) Choose start and end to calculate possible routes

2) Digibus<sup>®</sup> is displayed as part of the routes (overview and detailed view)  
©ÖBB

3) Integrated booking of ticket © ÖBB



- ✓ Successful demonstration of the whole digital mobility chain
- ✓ **Real life demonstration** in Koppl 2020 (Connection to regional transport line, operators from Postbus, 7 weeks trial)
- ✓ Integration of realtime-data (ÖBB - ITCS)

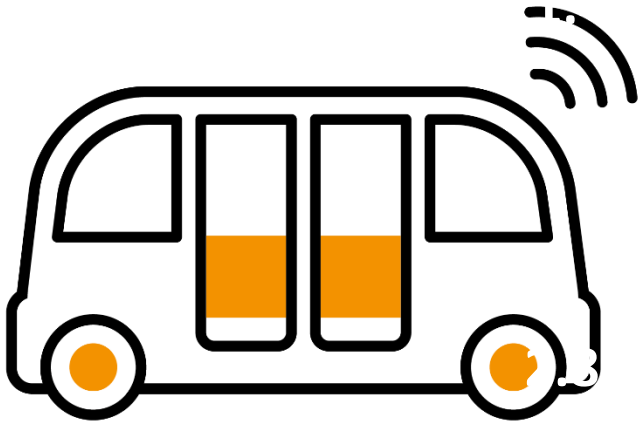
# Phase V: Evaluation



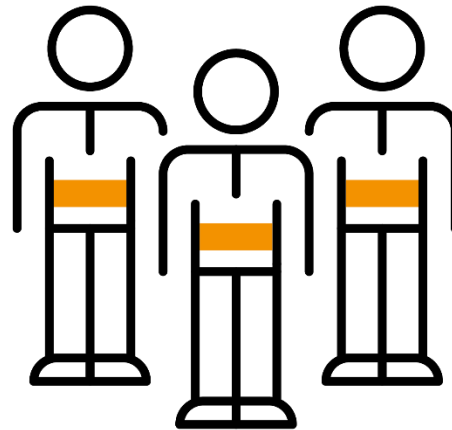
- Which potentials exist for automated shuttles?
- What did we learn from the trials?



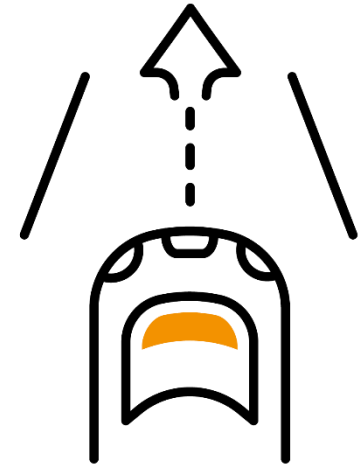
# Phase V: Real-world Trials



1.423  
test drives



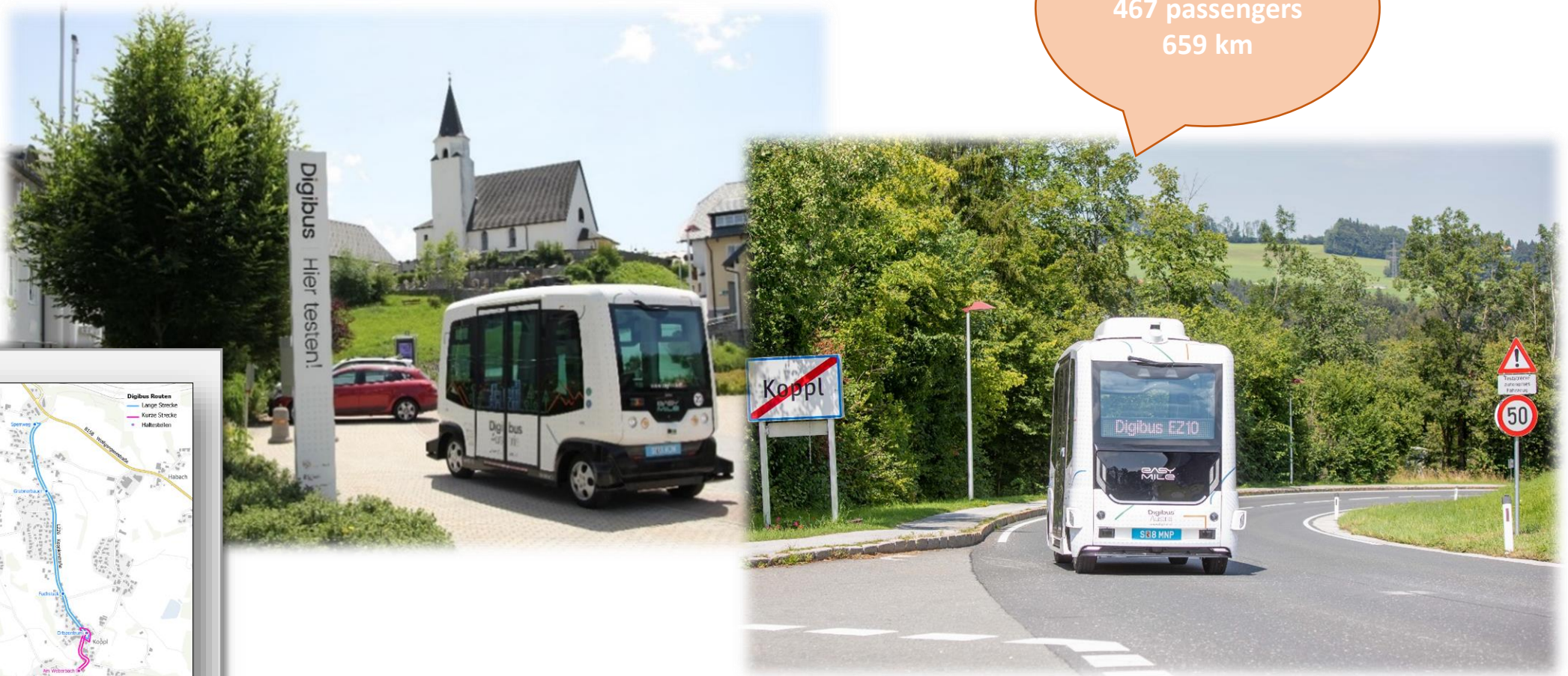
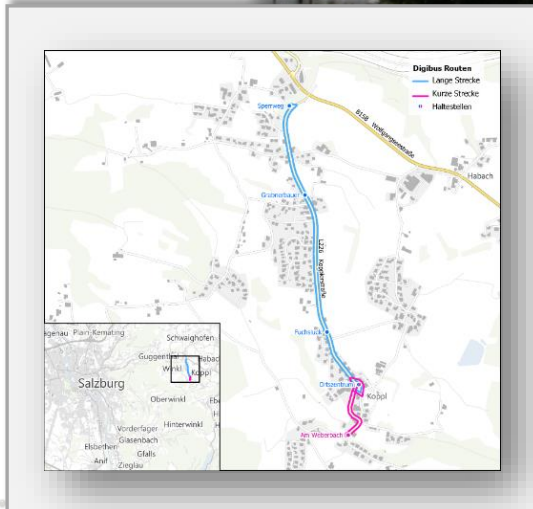
2.895  
passengers



1.290  
kilometer

# Phase V: Trial on public roads

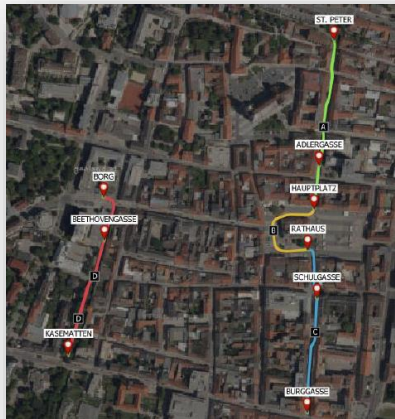
331 test drives  
467 passengers  
659 km





# Phase V: Trial on public roads

969 test drives  
2.243 passengers  
620 km



2021/05/19

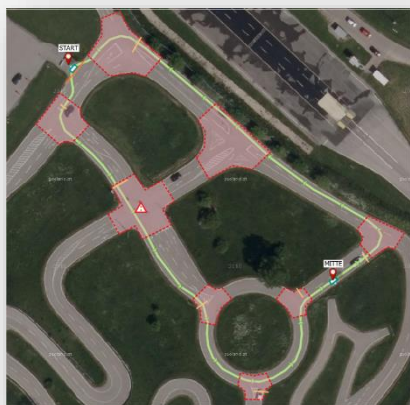
Wiener Neustadt, Lower Austria



# Phase V: Trial on non-public test track



55 test drives  
136 passengers



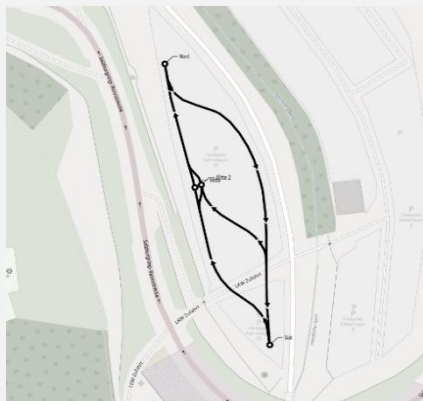
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ÖAMTC Drive Center Teesdorf, Lower Austria

# Phase V: Trial on non-public test track



68 test drives  
49 passengers  
10,5 km



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Salzburgring, Koppl, Salzburg



# Phase V: Trial on private parking site

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Austria

20 test drives  
29 passengers  
4,6 km



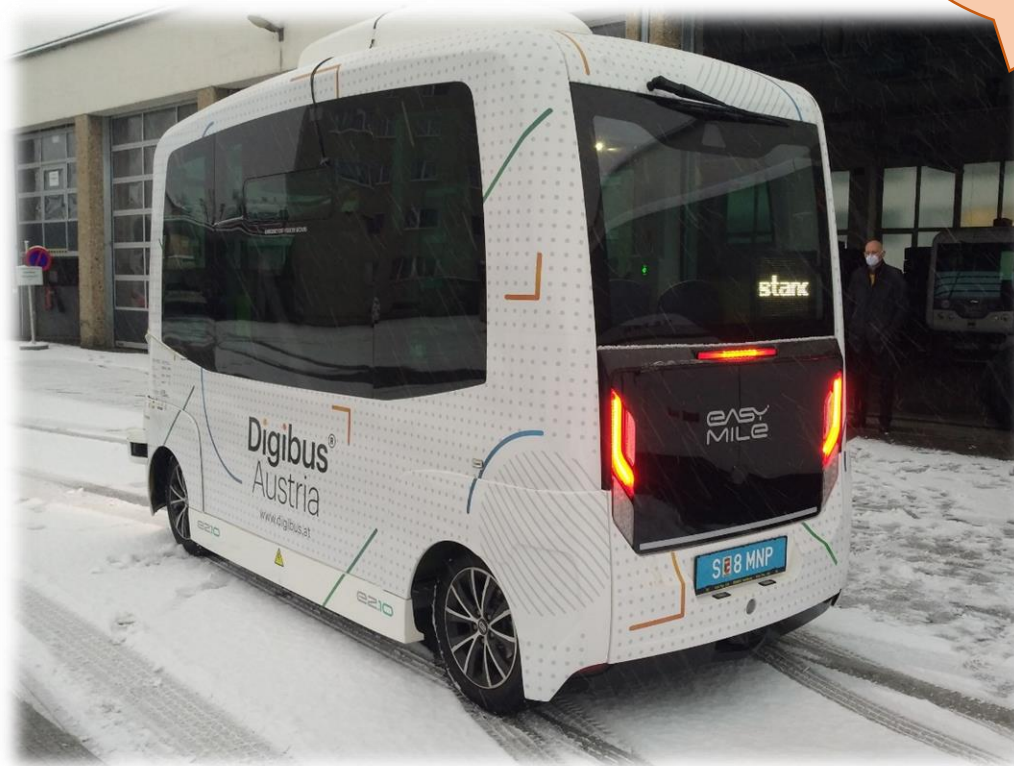
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Private parking of Commend International,  
Salzburg

# Phase V: Trial in bus depot

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24 test drives  
13 passengers  
7,7 km



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Bus depot of Postbus, Salzburg

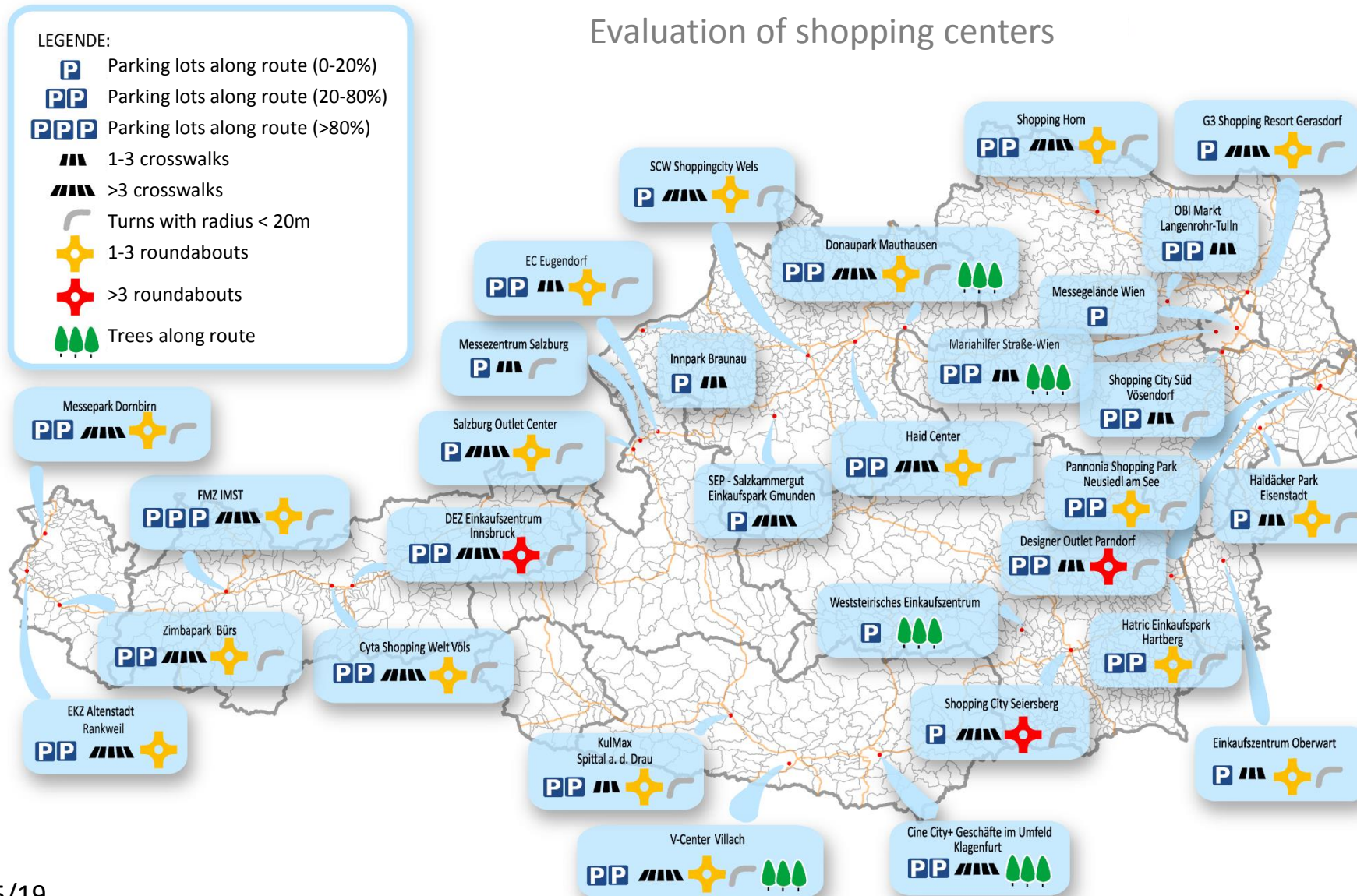
# Phase V: Learnings (condensed)

- Planning/preparation
  - Clear vision and driving factors needed
  - Collaboration of all stakeholders
  - Minimization of risks
  - High personal demand
  - Proprietary methods, missing standards
- Vehicles
  - Prototypes
  - High costs
- Test drives
  - Low speed (< 20km/h)
  - High complexity of driving maneuvers
  - Manual interventions needed
  - Highly demanding for operators
  - Mixed traffic as challenge
  - Challenges from environmental conditions
- Passengers
  - Variety of reactions (enthusiastic to denial)
  - 90% of passenger felt safe (most probably because of the operator onboard)

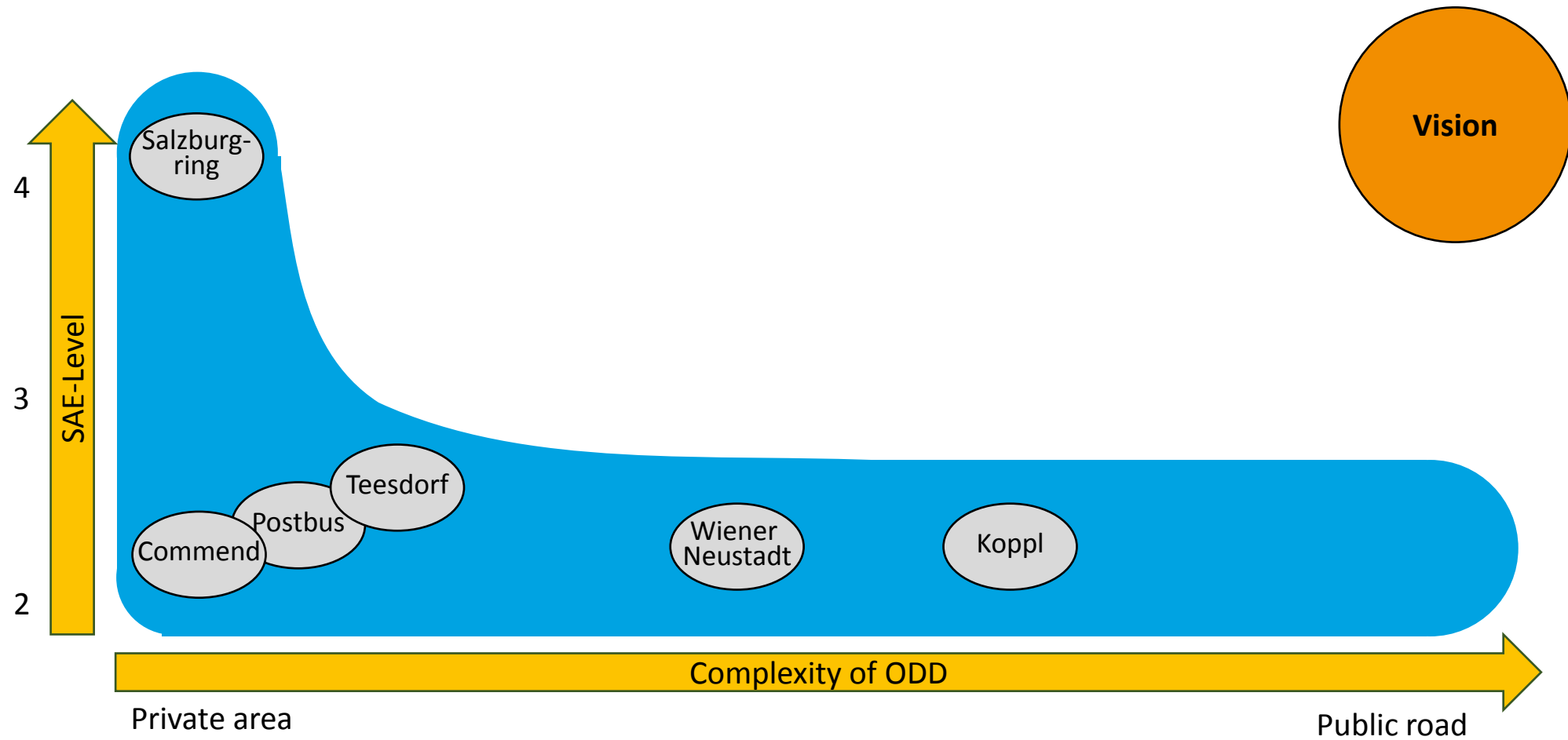


# Phase V: Potentials of automated shuttles

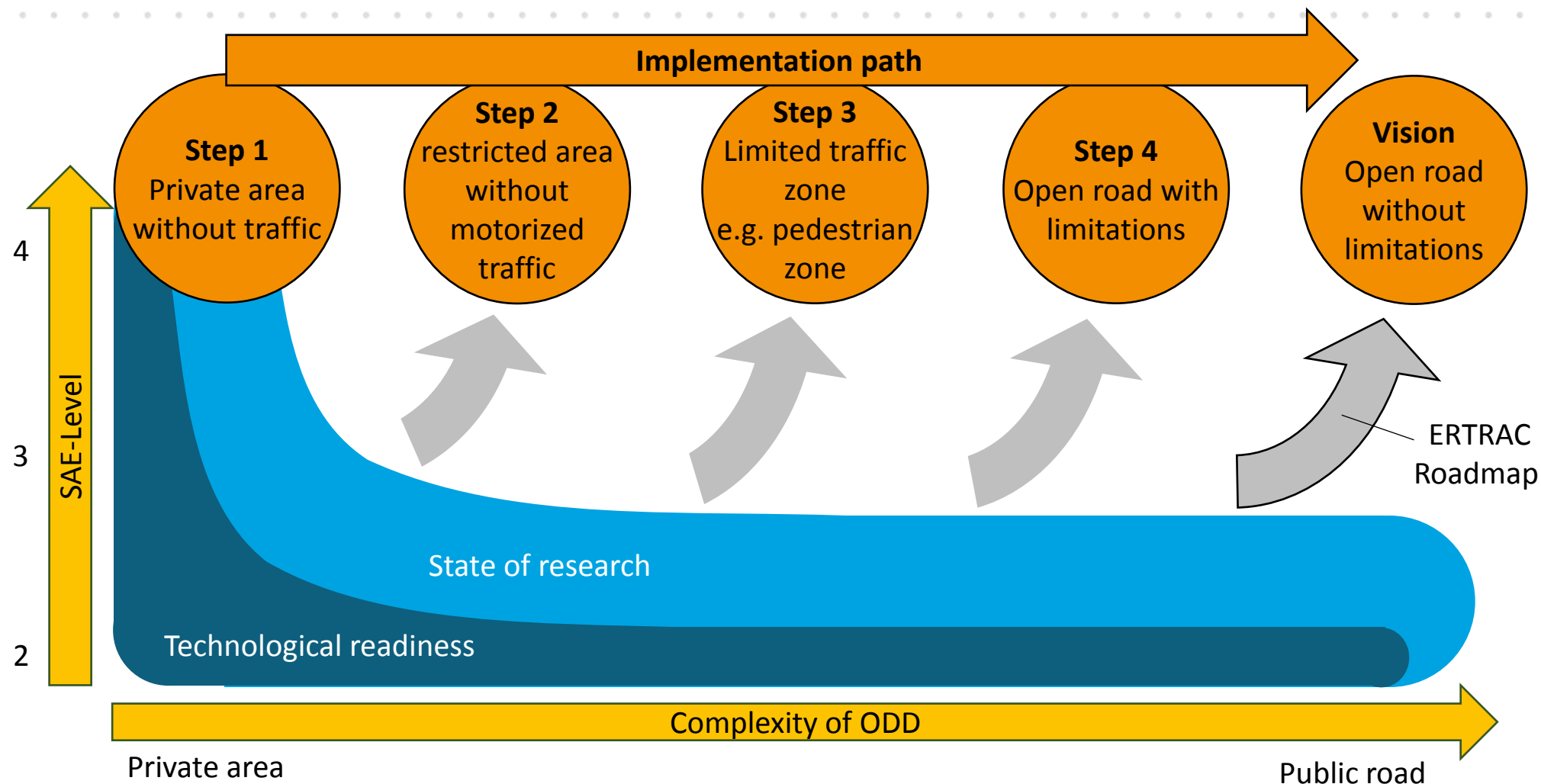
## Evaluation of shopping centers



# Phase V: The next steps – Vision and Status Quo



# Phase V: The next steps – Vision and Status Quo





# Results and experiences

<https://www.digibus.at/en/results-and-experiences/>

## Results and experiences

Results from the Austrian flagship project Digibus® Austria incl. predecessor project:

### Project Video with Results

Österreichisches Leitprojekt Digibus® Austria



### Publications

Organisation	Zitat	Konferenz	Download
Salzburg Research	Cornelia Zankl, Karl Rehl (2018): <b>Digibus 2017: Experiences with the first self-driving shuttlebus on open roads in Austria.</b>	Paper und Vortrag bei Transport Research Arena (TRA) in Wien, Session: Automated Transport: Concepts, Applications, Results	Siehe Seitenende
Salzburg Research	Rehl, K., Zankl, C. <b>Digibus®: results from the first self-driving shuttle trial on a public road in Austria.</b> Eur. Transp. Res. Rev. 10, 51 (2018).	Paper publiziert bei ETRR (European Transport Research Review) als eines der Top paper der TRA	<a href="https://doi.org/10.1186/s12544-018-0326-4">HTTPS://DOI.ORG/10.1186/s12544-018-0326-4</a>
Salzburg Research	Rehl, K. (2018): Special Interest Session; <b>"EU SIS23 Deployment of autonomous shuttles on public roads Experiences from five different countries".</b>	ITS World Congress 2018, Copenhagen	[coming soon]

### Contact details

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#### Coordinator



#### Associated Partners



#### Funded by

